

Privacy in Visual Data

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Privacy and its Protection

- Privacy is related to “the ability to **seclude themselves**, or **information about themselves**”
 - highly subjective and context dependent
- Privacy has a **significant impact on society**
 - addressed in numerous fields
 - controversially discussed
- Privacy is **increasingly at risk**
 - Technological advances, limited awareness, change in politics



Ubiquity of Cameras

- We are surrounded by **billions of cameras** in public, private and business
- **Huge amounts of image/video** data is endlessly captured and shared
- **Analysis and networking capabilities** advance at astonishing rates
- Limited **awareness about privacy threats**



Privacy in Data(bases)

- Draw conclusions for the **entire population** (or parts of) but **avoid linkage of sensitive information** to individuals

Name	SSN	Age	ZIP	Sex	Disease
[REDACTED]	[REDACTED]	[30,39]	9***	female	Flu
[REDACTED]	[REDACTED]	[40,49]	9***	male	Cancer
[REDACTED]	[REDACTED]	[30,39]	9***	female	Flu
[REDACTED]	[REDACTED]	[40,49]	9***	male	Flu
...

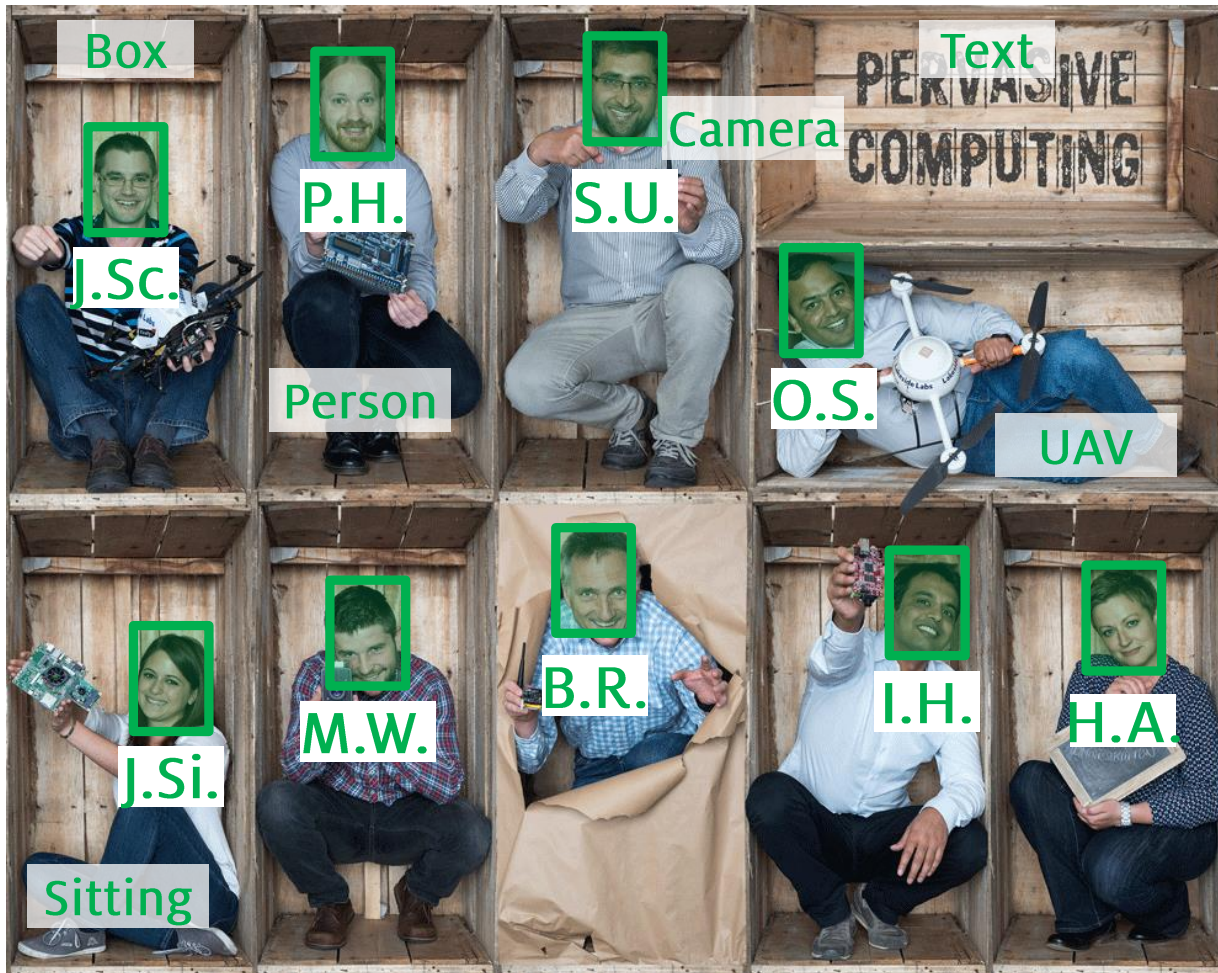
Explicit identifier

Quasi identifier

Sensitive information

- **Anonymization** as key protection method
- Modify quasi identifier to achieve **k anonymity**

Privacy in Visual Data



Who is there?

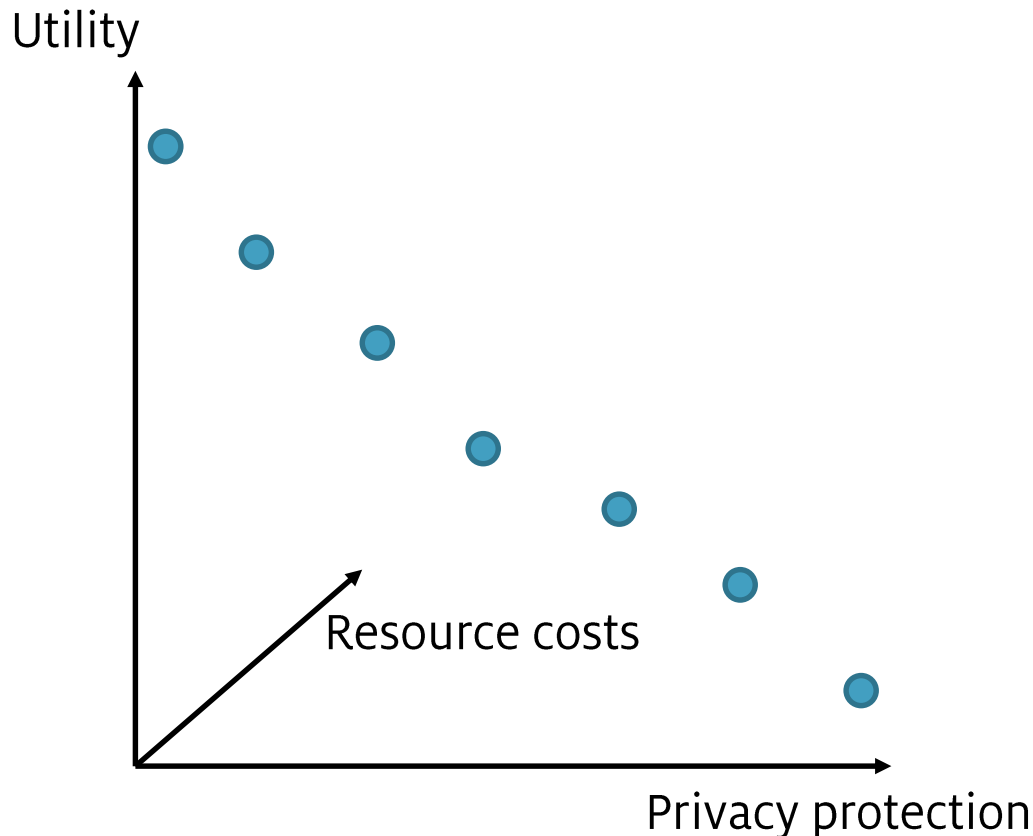
- (Quasi-) Identifiers
- Body or face regions

What is shown?

- Sensitive information
- Presence, „show an object“
„captured in a box“

How to avoid linkage of sensitive information to individuals?

Utility and Privacy Tradeoff



Distortion as key protection method

- Blanking
- Pixelation
- Blurring
- Cartooning

Utility dependent on level of distortion

- Similarity
- Appearance
- Detectability

No single **best protection** method available

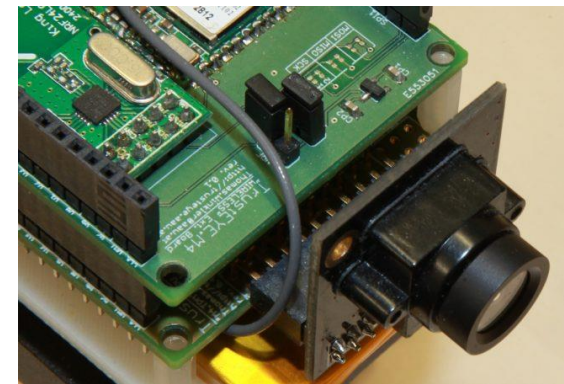
Agenda

1. What **distortion method** to use in **aerial imagery**?
 - Explore utility/privacy/cost design space
 - Adapt filter strength for recreational images
 - Measure achieved privacy protection and utility

2. How to **securely implement** privacy protection?
 - Apply security methods at sensory edge
 - Rely on hardware-supported protection



[www.radiogong.de]



[Winkler, Rinner. [Security and Privacy Protection in Visual Sensor Networks: A Survey](#). ACM Computing Surveys. 2014.]

#1 Privacy Protection in Recreational Aerial Images



Recreational Airborne Cameras

- **Micro Aerial Vehicles (MAVs)** are becoming common in public places for recreational and business video capturing with high-resolution cameras
- How can we **protect privacy** while **maintaining high fidelity** of visual data?
- Exploring the privacy design space
 - When is protection necessary at all?
- Configuring an adaptive privacy filter
 - What is the minimal protection?



www.hexaplus.com



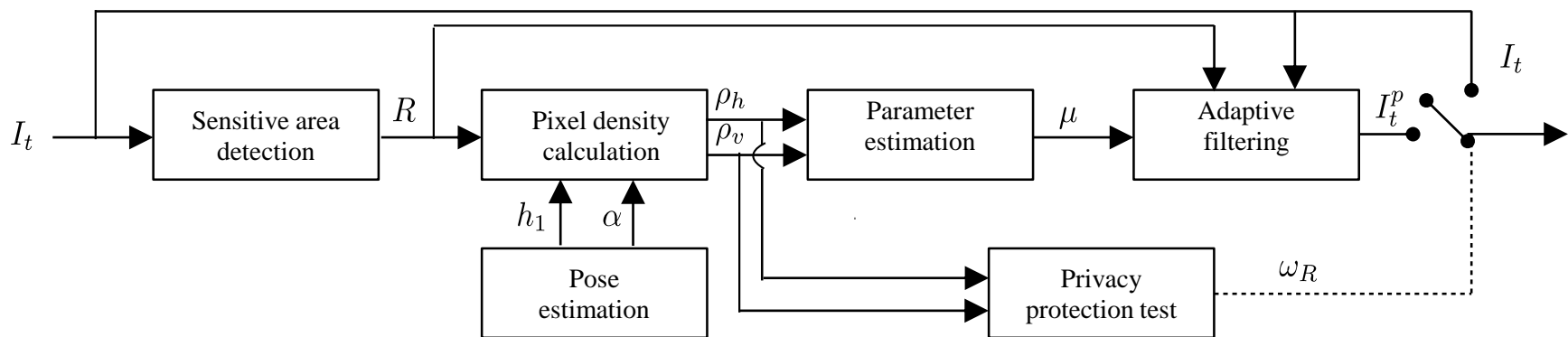
www.airdog.com



www.kickstarter.com

Adapt Blur to Target Resolution

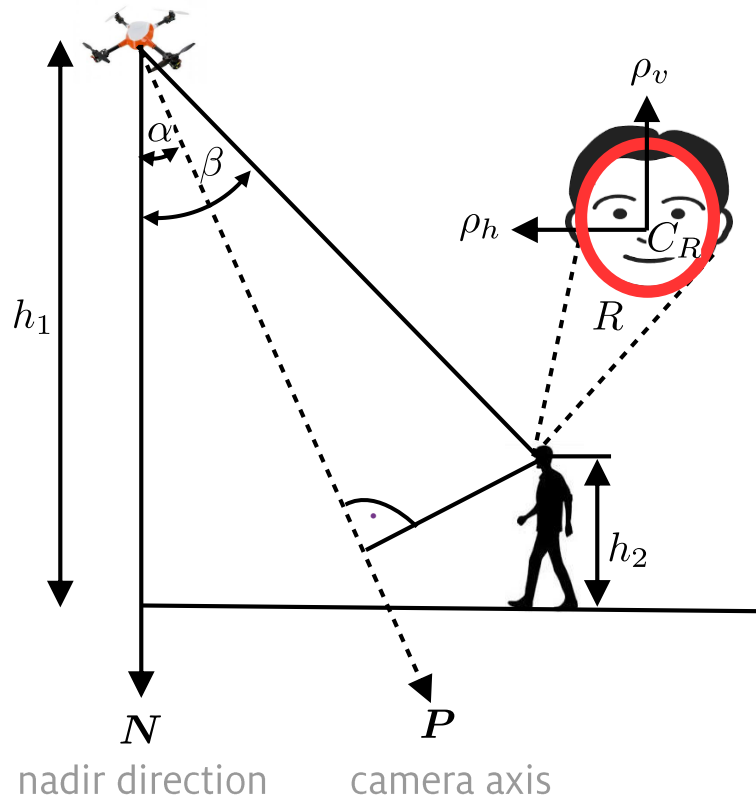
- Privacy **design space exploration** with adaptive filtering
 - Determine target's pixel density based on camera pose
 - Decide whether target is inherently protected
 - Configure privacy protection filter
 - Perform adaptive filtering
- Studied for **aerial images**



[Sawar, Rinner, Cavallaro. [Design Space Exploration for Adaptive Privacy Protection in Airborne Images](#). In Proc. AVSS 2016.]

Pixel Density Estimation

- Horizontal and vertical density at target center



focal length

$$\rho_h = \frac{f \cos(\beta)}{p_h (h_1 - h_2)}$$

horizontal pixel size

$$\rho_v \approx \frac{f \cos(\beta) \sin(\beta)}{p_v (h_1 - h_2)}$$

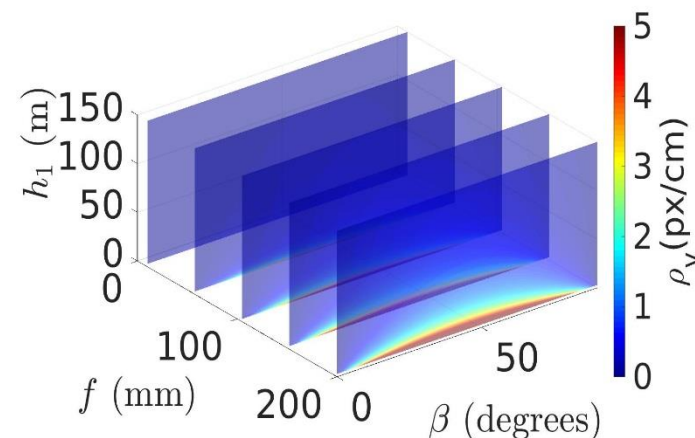
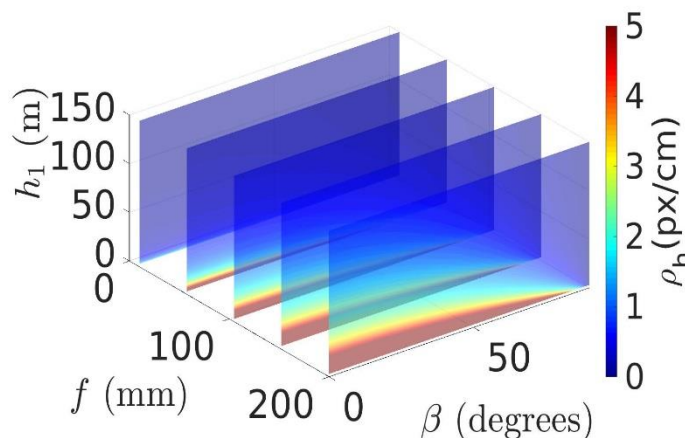
vertical pixel size

Privacy Design Space

- Region protected ($\omega_R=0$), if horizontal or vertical density is below threshold

$$\omega_R = \begin{cases} 1 & \text{if } \rho_h > \rho_h^0 \ \& \ \rho_v > \rho_v^0 \\ 0 & \text{otherwise} \end{cases}$$

- Pixel density values for different heights (3-150 m), focal lengths (10-200 mm) and viewing angles (0-90 degrees)
 - For Canon EOS 5 MkII camera

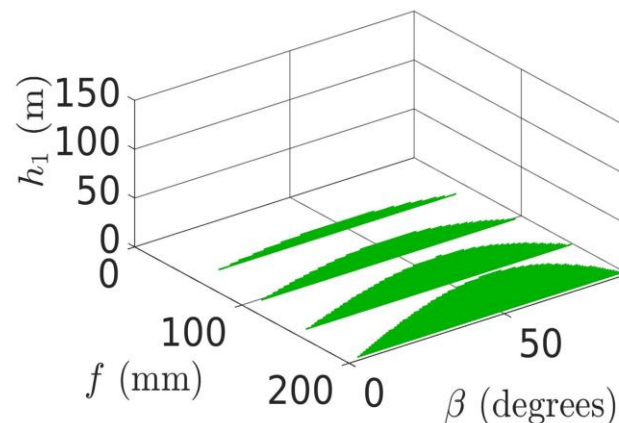


Privacy Design Space

- Region protected ($\omega_R=0$), if horizontal or vertical density is below threshold

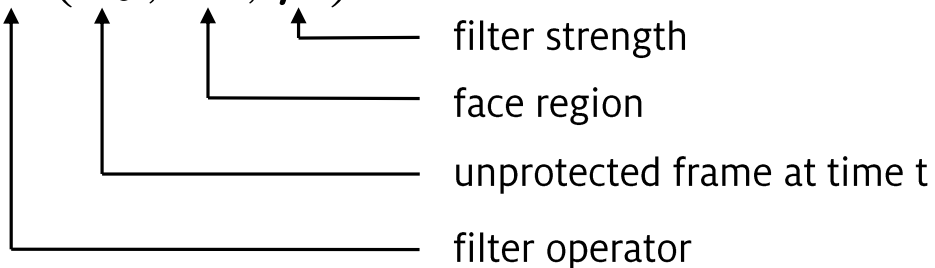
$$\omega_R = \begin{cases} 1 & \text{if } \rho_h > \rho_h^0 \ \& \ \rho_v > \rho_v^0 \\ 0 & \text{otherwise} \end{cases}$$

- Separation between privacy sensitive and inherently protected space
 - For given threshold values (shown for $\rho_h^0 = \rho_v^0 = 1 \text{ px/cm}$)



Adaptive Privacy Filter

- Configure filter \mathcal{G} so that privacy protection is increased while fidelity is maintained

$$I_t^P = \mathcal{G}(I_t, R, \mu)$$


filter strength
 face region
 unprotected frame at time t
 filter operator

- Determine **filter strength** μ such that the pixel resolution in the protected image is just below the threshold

Gaussian Blur as Privacy Filter

- Approximated anisotropic Gaussian kernel

$$g(v, h) = \frac{1}{2\pi\sigma_v\sigma_h} e^{-\left(\frac{v^2}{2\sigma_v^2} + \frac{h^2}{2\sigma_h^2}\right)}$$

with

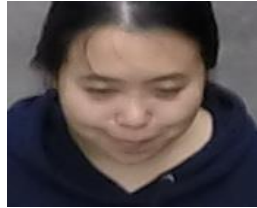
$$\sigma_i = \frac{3\rho_i}{\pi\rho_i^0} \text{ where } i \in \{v, h\}$$

- Filtering with kernel size

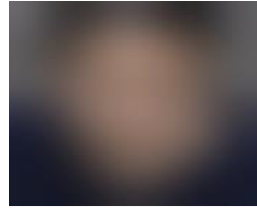
$$\mu_i = 2\lceil 3\sigma_i \rceil + 1$$

useful information in I_t^p is reduced to the threshold ρ_i^0

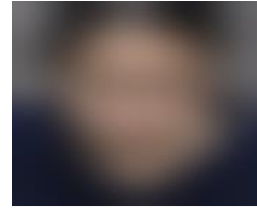
Adaptive Gaussian Blur Example



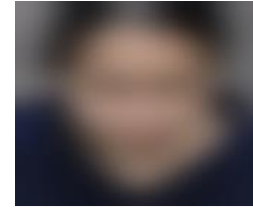
$\rho: (5.03, 3.88)$



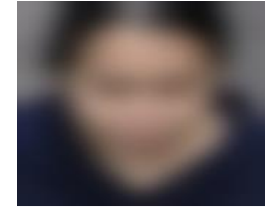
$\mu: (121, 105)$



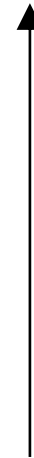
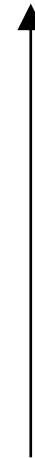
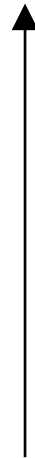
$\mu: (99, 77)$



$\mu: (75, 57)$



$\mu: (59, 47)$



Original

Fixed

Over

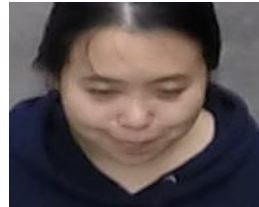
Optimal

Under

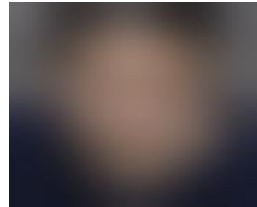
Gaussian blur for LDA face recognizer

Fixed: w.r.t. highest pixel density image in the data

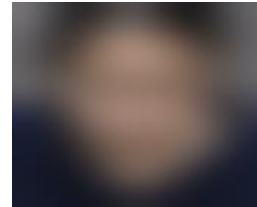
Adaptive Gaussian Blur Example



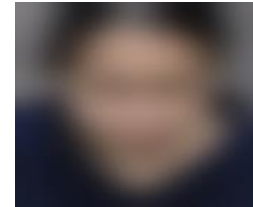
$\rho: (5.03, 3.88)$



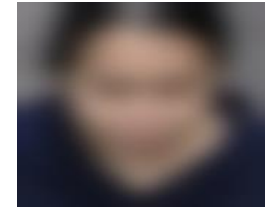
$\mu: (121, 105)$



$\mu: (99, 77)$



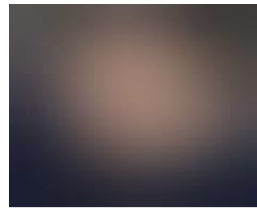
$\mu: (75, 57)$



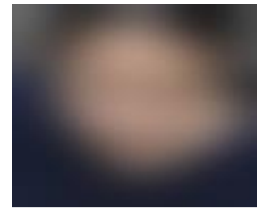
$\mu: (59, 47)$



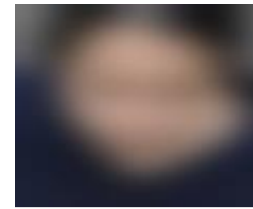
$\rho: (3.96, 2.87)$



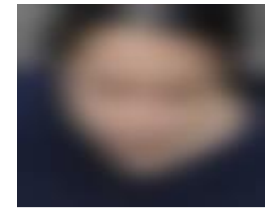
$\mu: (121, 105)$



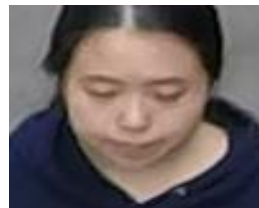
$\mu: (75, 57)$



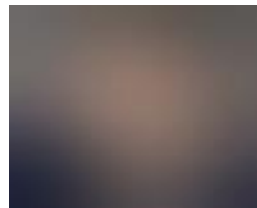
$\mu: (59, 43)$



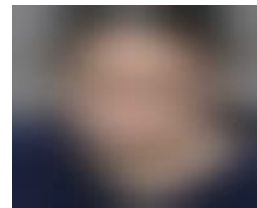
$\mu: (47, 35)$



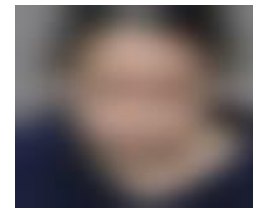
$\rho: (3.06, 2.28)$



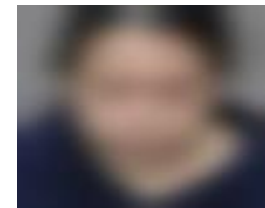
$\mu: (121, 105)$



$\mu: (61, 45)$



$\mu: (45, 35)$



$\mu: (37, 29)$

Original

Fixed*

Over*

Optimal*

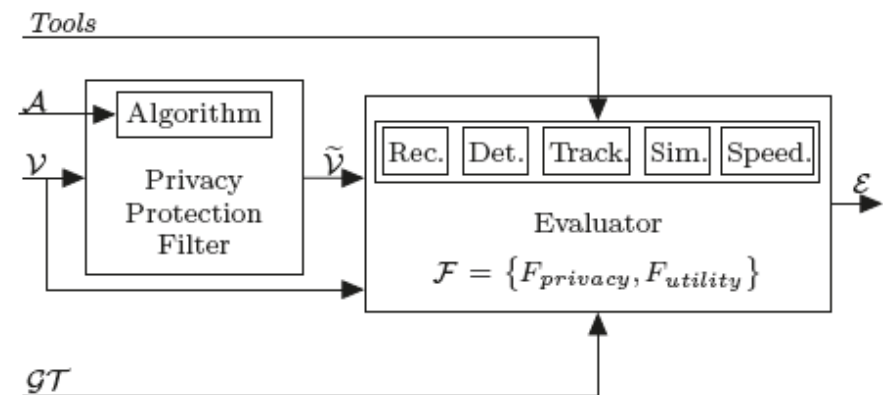
Under*

*Gaussian Blur for LDA face recognizer

Fixed: w.r.t. highest pixel density image in the data

Measuring Privacy & Utility

- Subjective methods based on user studies
 - Predefined criteria
 - Crowd approaches
- Objective methods exploit CV algorithms
 - Detectors, classifiers, recognizers etc.
 - Metric based on performance difference between protected and unprotected input
 - Do not consider context or side-channel information



[Erdelyi, Winkler, Rinner. [Privacy Protection vs. Utility in Visual Data: An Objective Evaluation Framework](#). Multimedia Tools and Applications, 2017.]

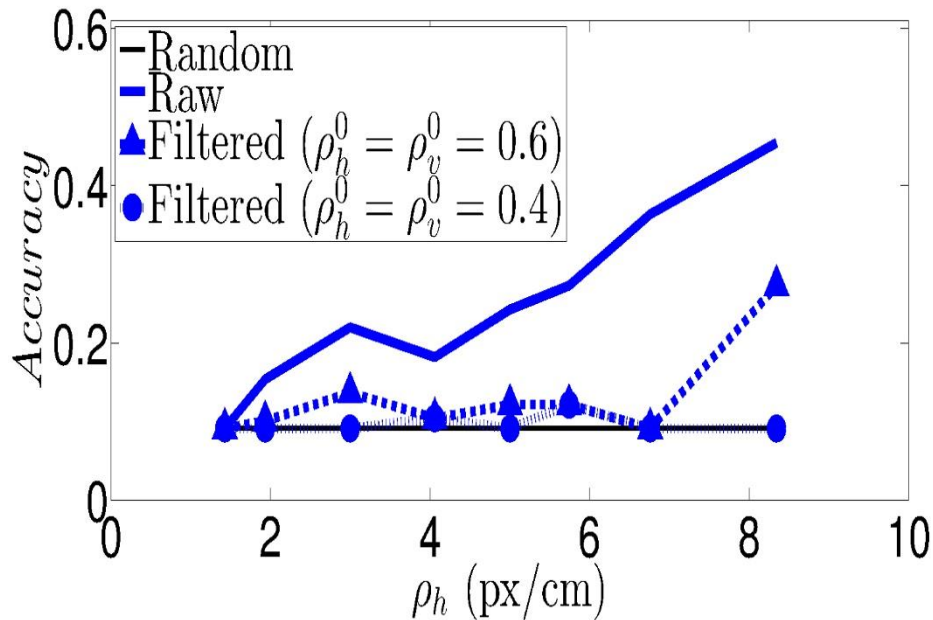
Experimental Setup

- Dataset from [Hsu, 2015]
 - Population size: 11 persons
 - Test data: 693 (63 x 11) images collected from 63 different positions.
 - Training data: 121 images i.e. 11 images of each person.
- Popular face recognizers for **privacy measurement**:
 - Linear Discriminant Analysis (LDA) [Belhumeur, 1997]
 - Local Binary Patterns Histograms (LBPH) [Ahonen, 2006]
- **Fidelity measurement**:
 - Peak Signal to Noise Ratio (PSNR)
 - Structural Similarity Index metric (SSIM) [Wang 2004]

Privacy of adaptively blurred Faces

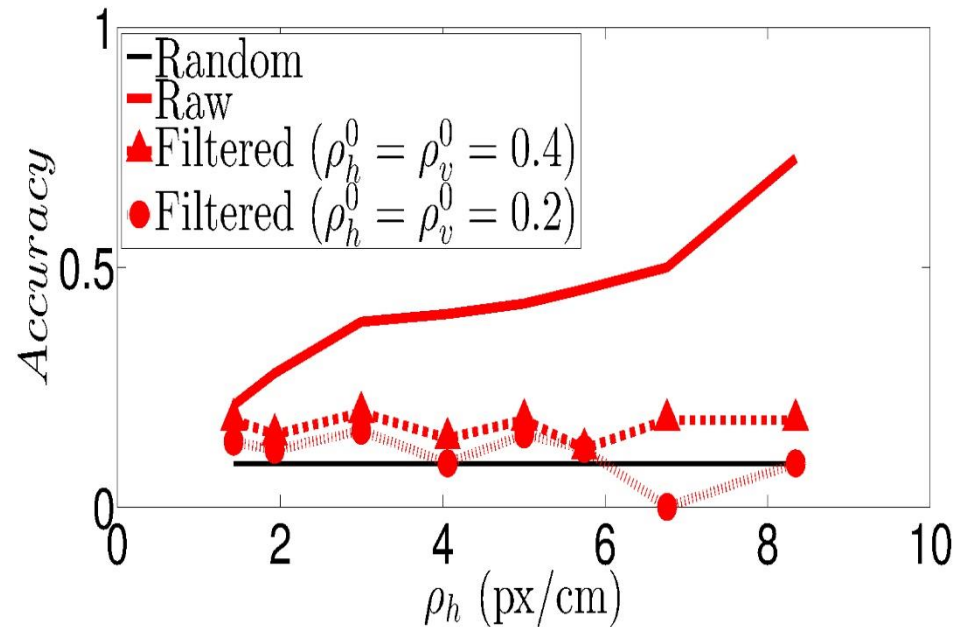
LDA face recognizer

Thresholds: 0,6 & 0.4 px/cm



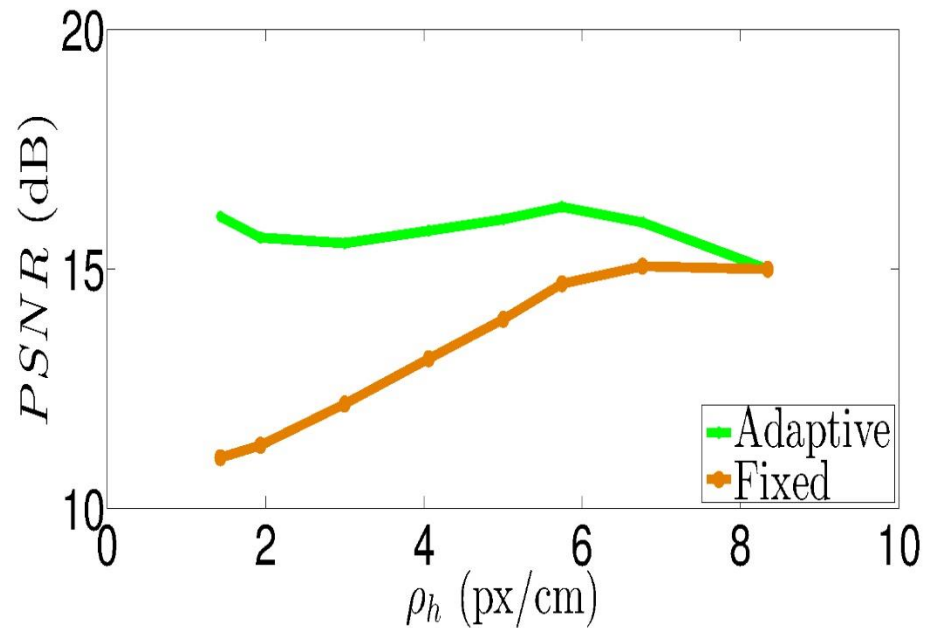
LBPH face recognizer

Thresholds: 0.4 & 0.2 px/cm

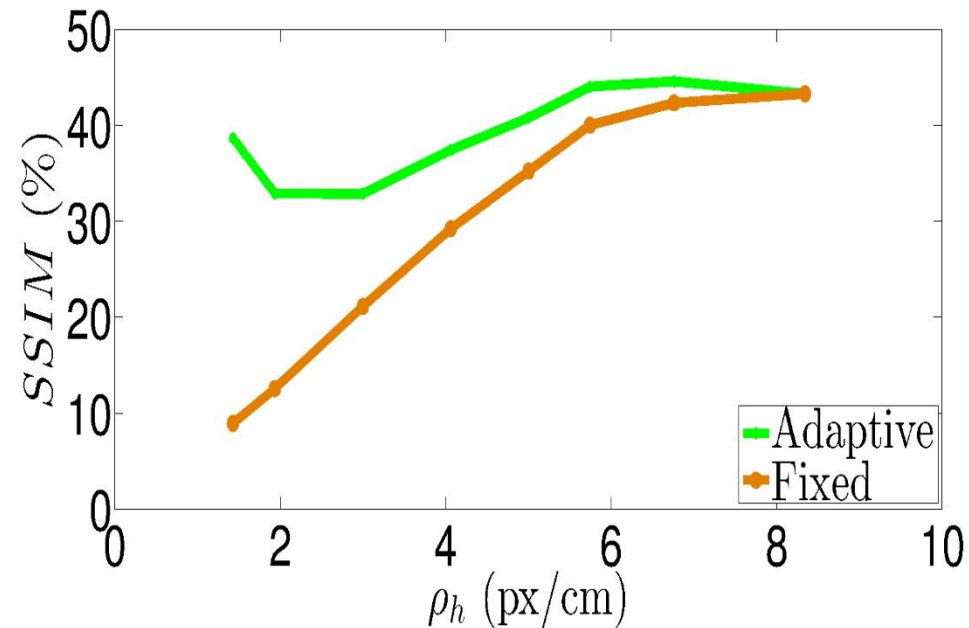


Fidelity Comparison

Peak Signal to Noise Ratio

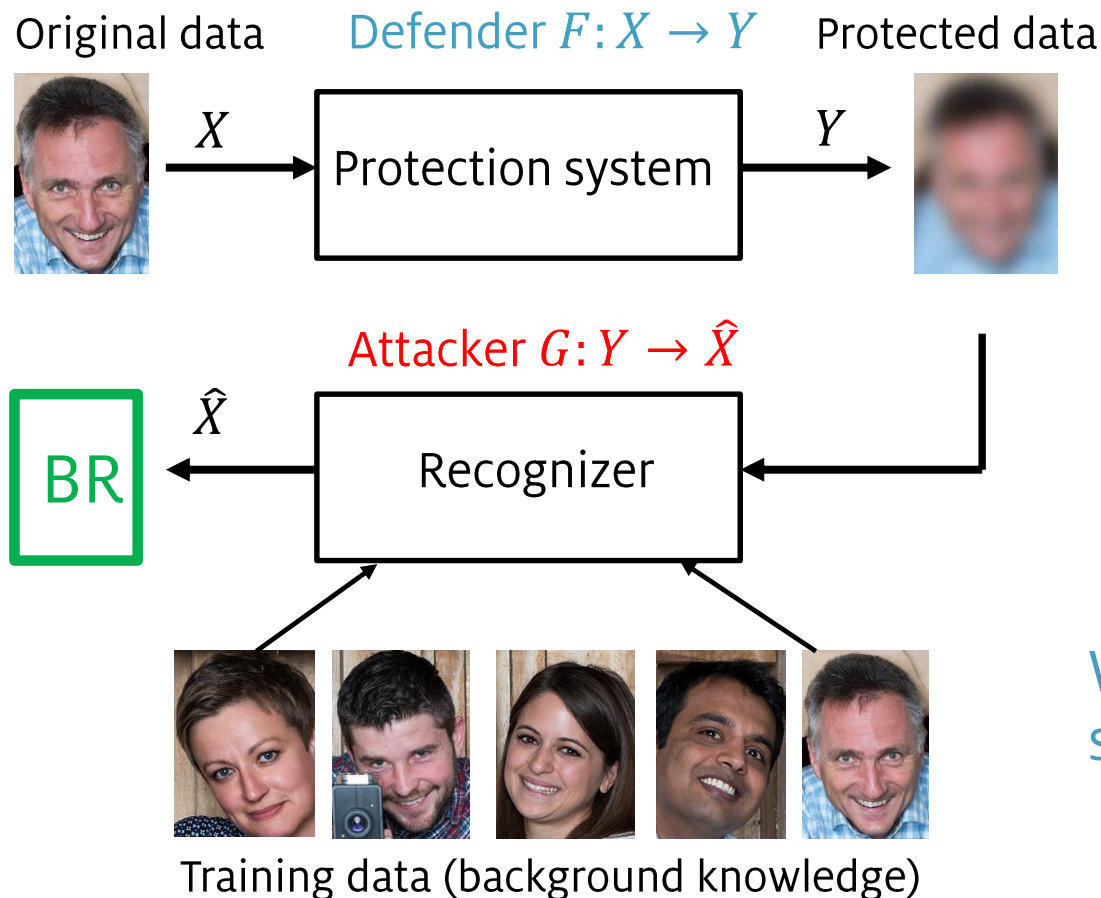


Structural Similarity Index



Privacy Attacks

Modelling privacy protection systems



Distortion (utility)

$$D = \lambda(X; Y)$$

Information leakage (privacy protection)

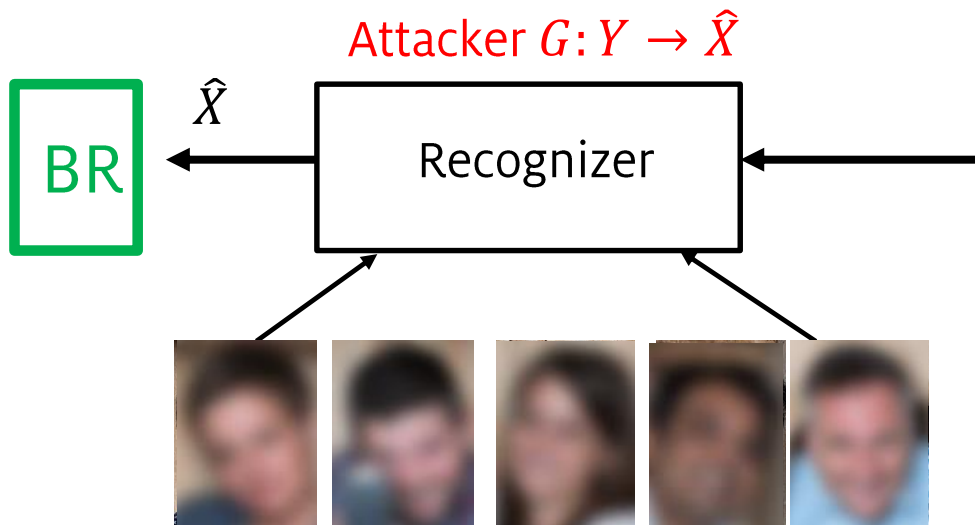
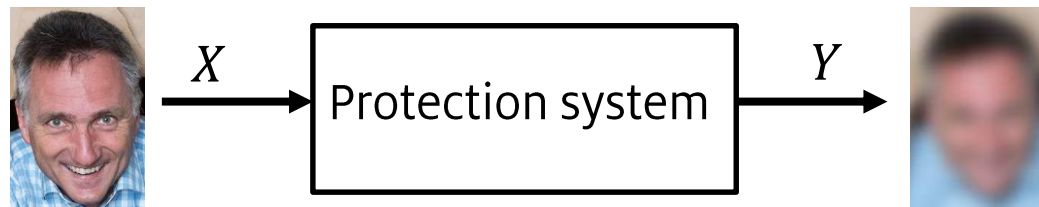
$$L = \lambda(X; \hat{X})$$

What if the attacker has some knowledge about F ?

Parrot Attacks

Attacker knows (learns) the **protection filter** (eg. blurring filter)

Original data Defender $F: X \rightarrow Y$ Protected data



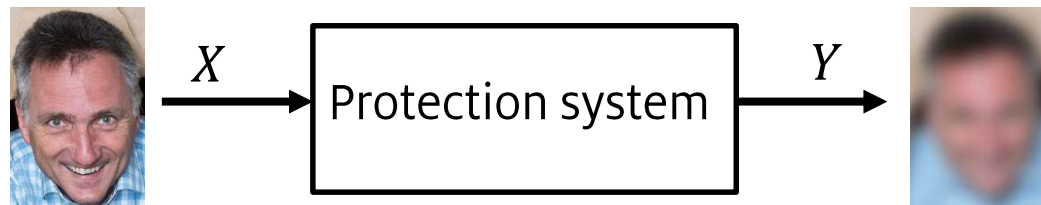
Train the recognizer in **protected domain**

- increase of information leakage

Reconstruction Attacks

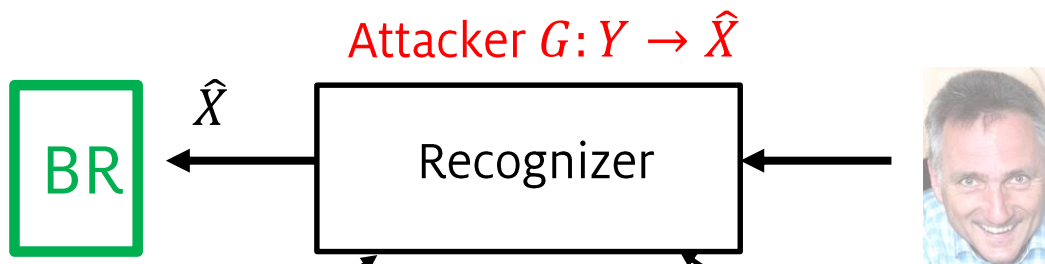
Attacker knows (learns) how to reconstruct original data

Original data Defender $F: X \rightarrow Y$ Protected data



Train reconstruction of protected data

- Eg., superresolution

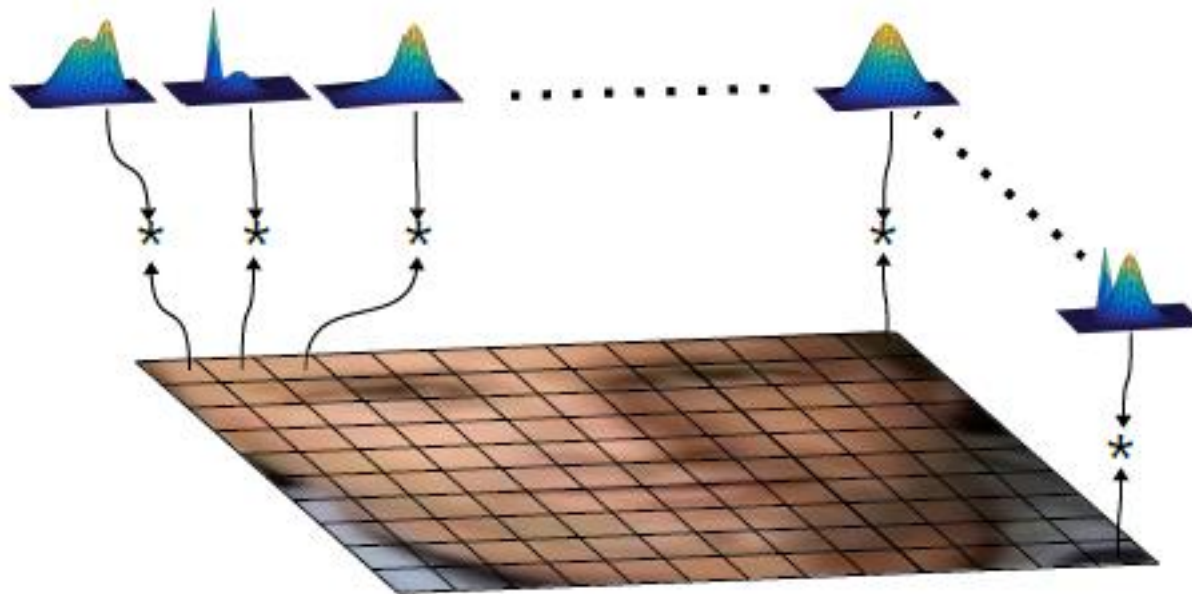


Training data (background knowledge)

Adaptive Blurring with Spatial Hopping (AHGMM)

Pseudo-randomly change filter parameters for small patches to hinder

- Estimation of filter parameter
- Reconstruction of original image



[Sawar, Rinner, Cavallaro. [Adaptive Hopping Gaussian Mixture Model for Privacy-Preserving Aerial Photography](#). Under review 2017.]

Experimental Setup

- Labelled Faces in the Wild Dataset
 - Population size: 5749 persons
 - Expanded for [aerial imagery](#)
40 instances for each person (variation in pitch angle and resolution)

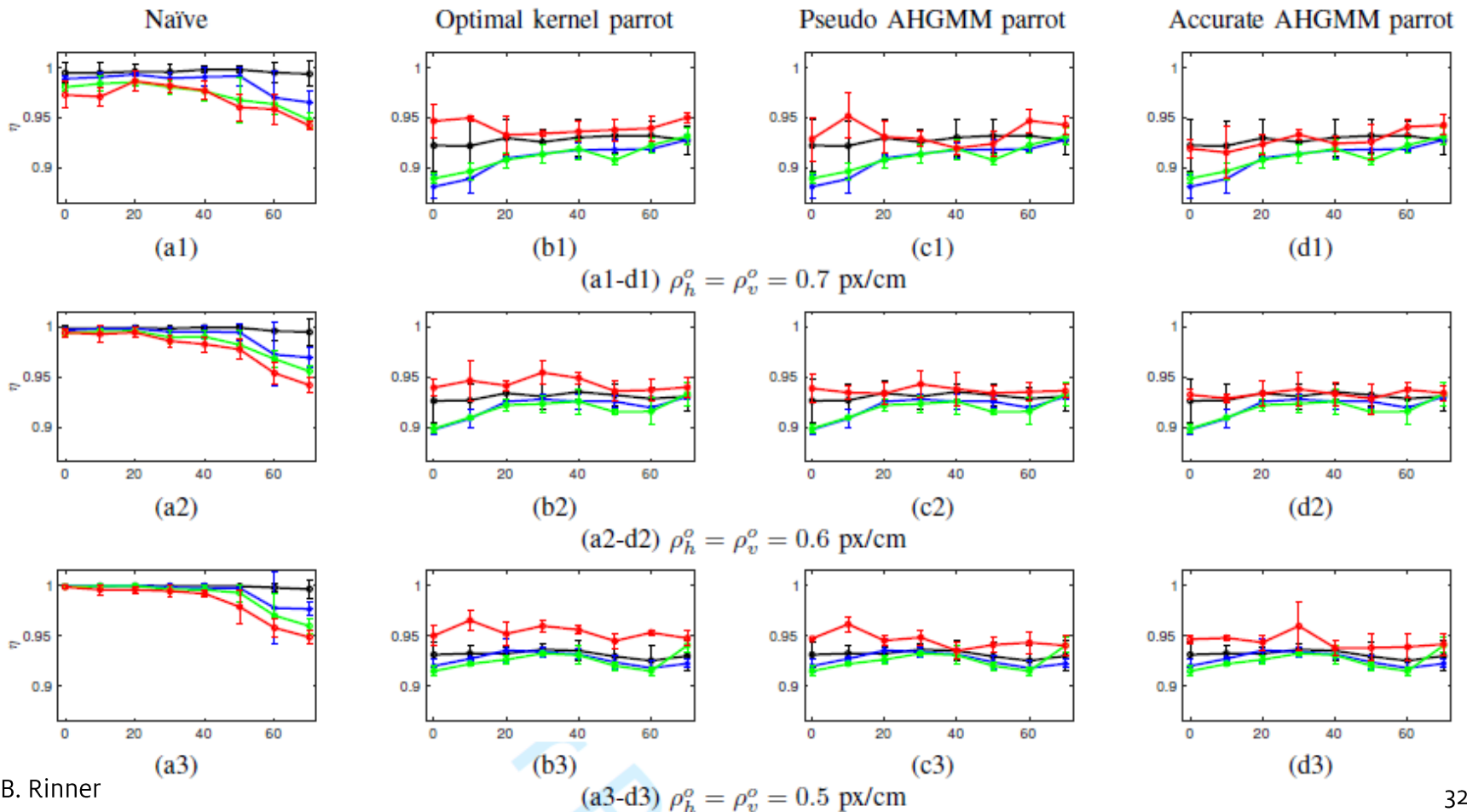


Experimental Setup (2)

- Privacy **attack scenarios**
 - Naïve: training with raw data
 - Parrot: training with AHGMM filtered data (3 variants)
 - **Pitch angle** is known by attacker as background
 - Tested with 380000 face images in total
- OpenFace recognizer for **privacy measurement**:
 - Verification test (600 persons with 10x cross validation)
- **Fidelity measurement**:
 - Peak Signal to Noise Ratio (PSNR)
 - Structural Similarity Index metric (SSIM) [Wang 2004]

Privacy Evaluation

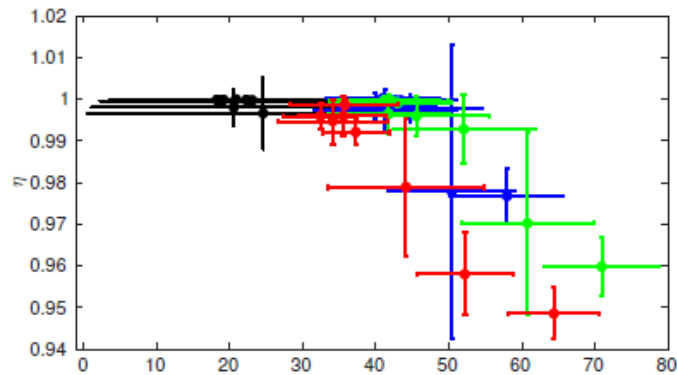
- Comparison with 3 state-of-the-art privacy filters (-AHGMM)
 - Charts: privacy level η vs. pitch angle; rows: different filter thresholds



Privacy/Utility Tradeoff

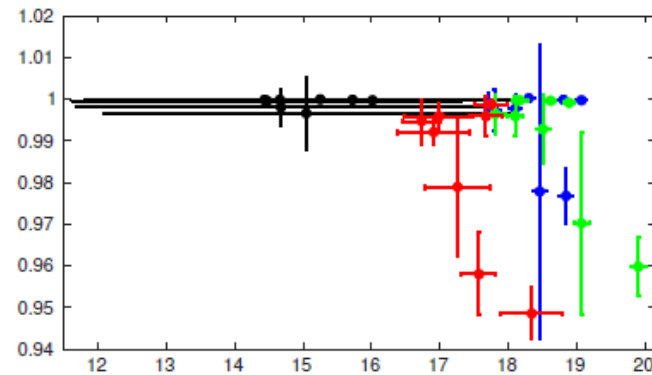
- Privacy level vs. utility compared with 3 privacy filters (-AHGMM)

SSIM (%)



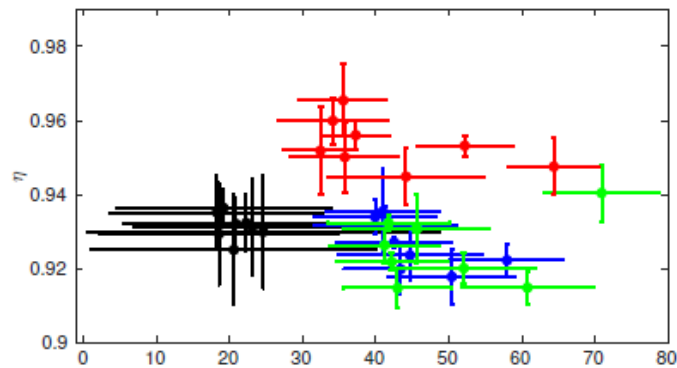
(a)

PSNR (dB)

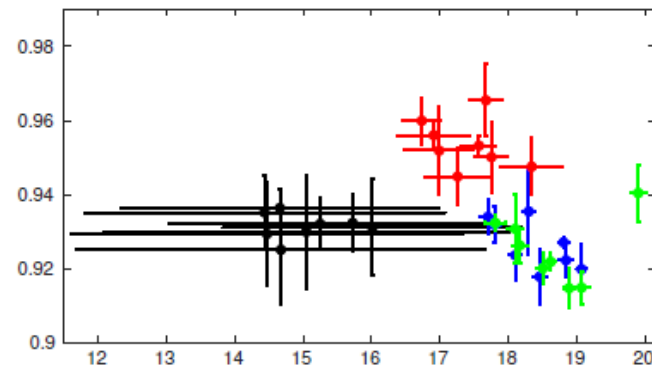


(b)

Naive attack



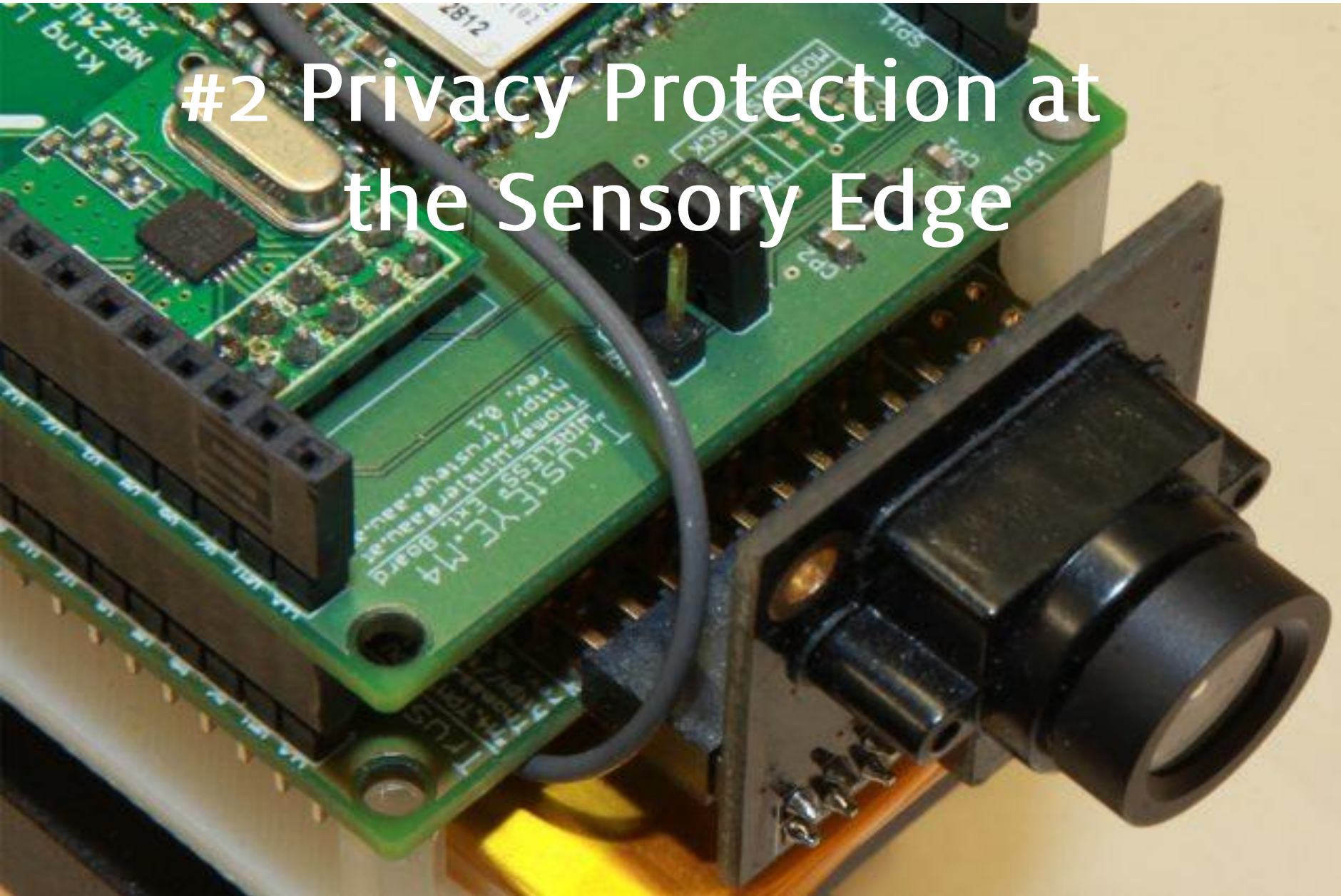
(c)



(d)

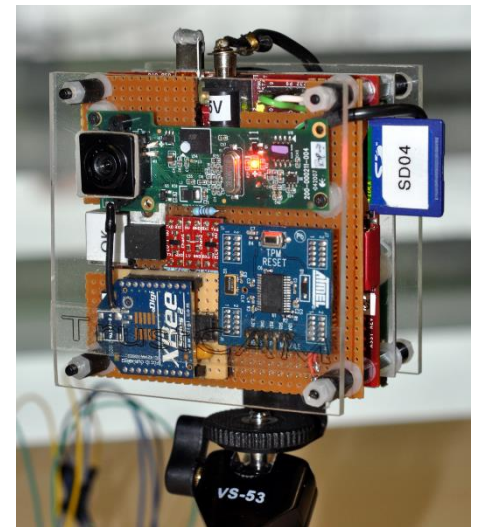
Parrot attack

#2 Privacy Protection at the Sensory Edge



Onboard Protection on Camera

- Most cameras have no onboard protection, rarely software protection
- TrustCAM with **TPM-based** security features
 - Trusted boot
 - Integrity/authenticity by TPM-protected RSA keys
 - Freshness/timestamping for outgoing images
 - Multi-level encryption as privacy protection
 - Authentic user feedback
- Successful feasibility study, but **security functionality was highly intertwined with application code**



[Winkler, Rinner. [Securing embedded smart cameras with trusted computing](#). EURASIP Journal on Wireless Communications and Networking, 2011]

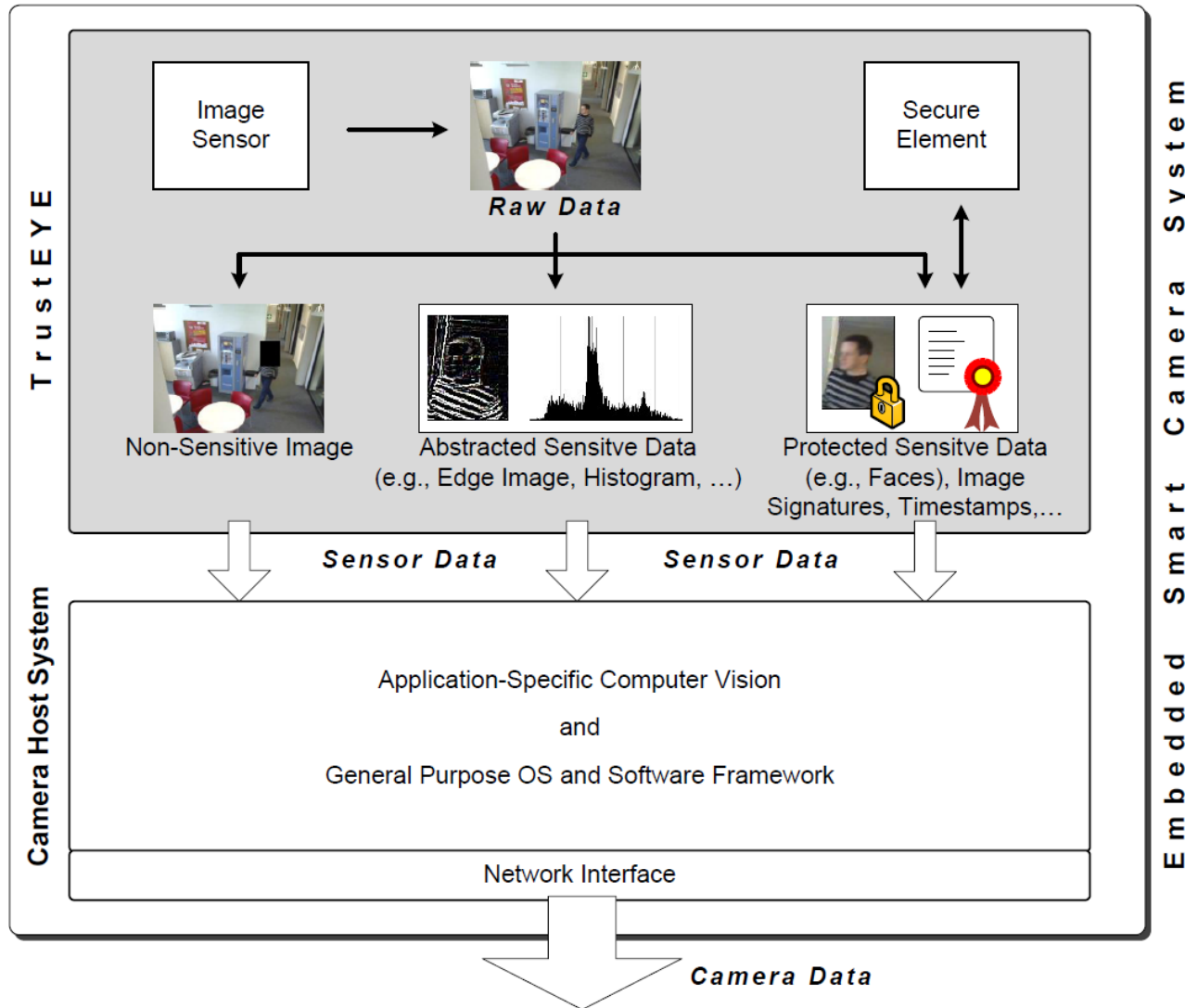
Secure and Privacy-aware Camera

- Vision: **TrustEYE** - security and privacy protection as a **feature of the image sensor** instead of the camera
- Benefits:
 - Sensor delivers **protected** and **pre-filtered** data
 - Strong separation btw. trusted and untrusted domains
 - Camera software does no longer have to be trustworthy
 - Security **can not be bypassed** by application developers
 - TrustEYE is **anchor for secure inter-camera collaboration**

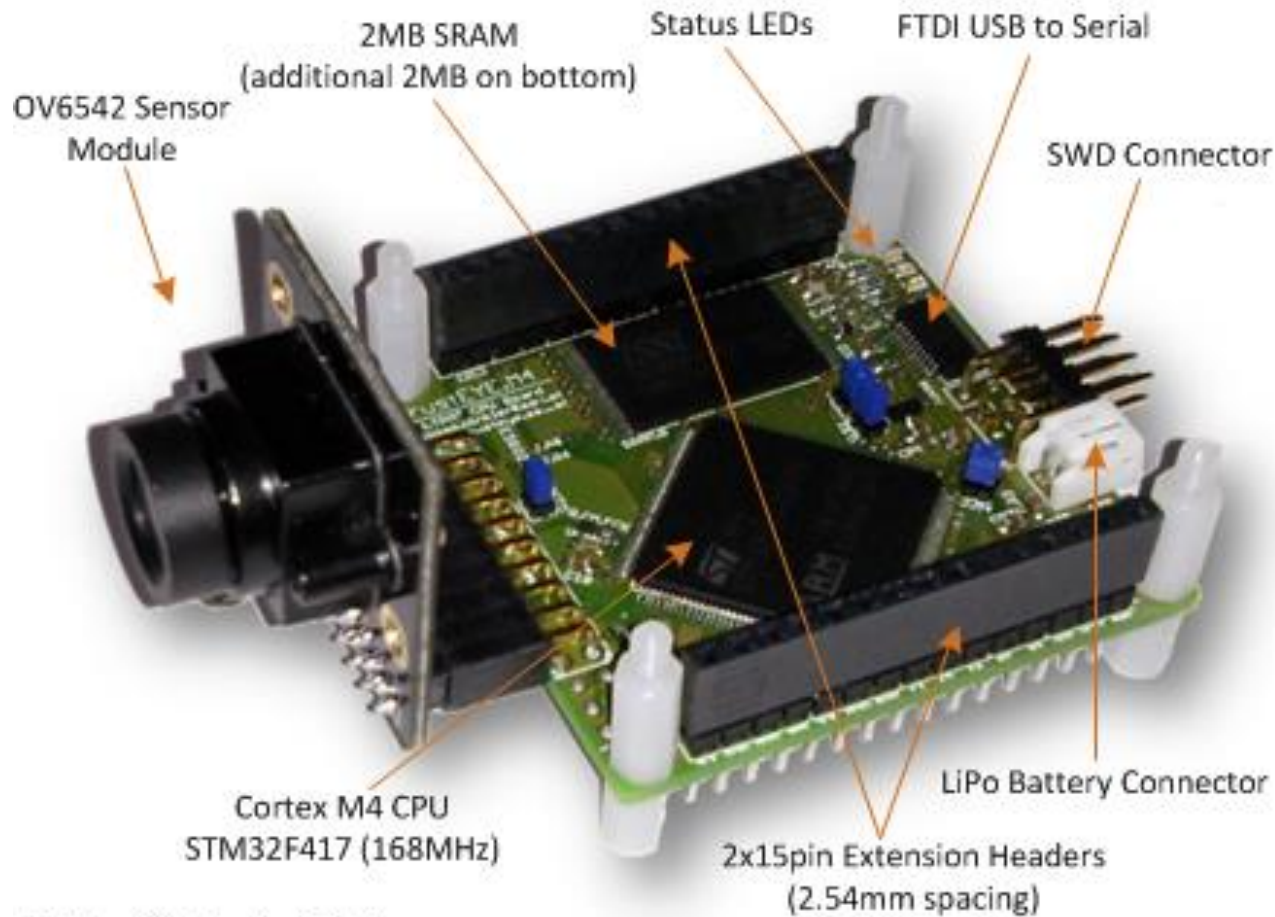
[Winkler, Erdelyi, Rinner. [TrustEYE.M4: Protecting the Sensor - not the Camera](#). In Proc. AVSS 2014]

<http://trusteye.aau.at/>

TrustEYE Architecture



TrustEYE Platform

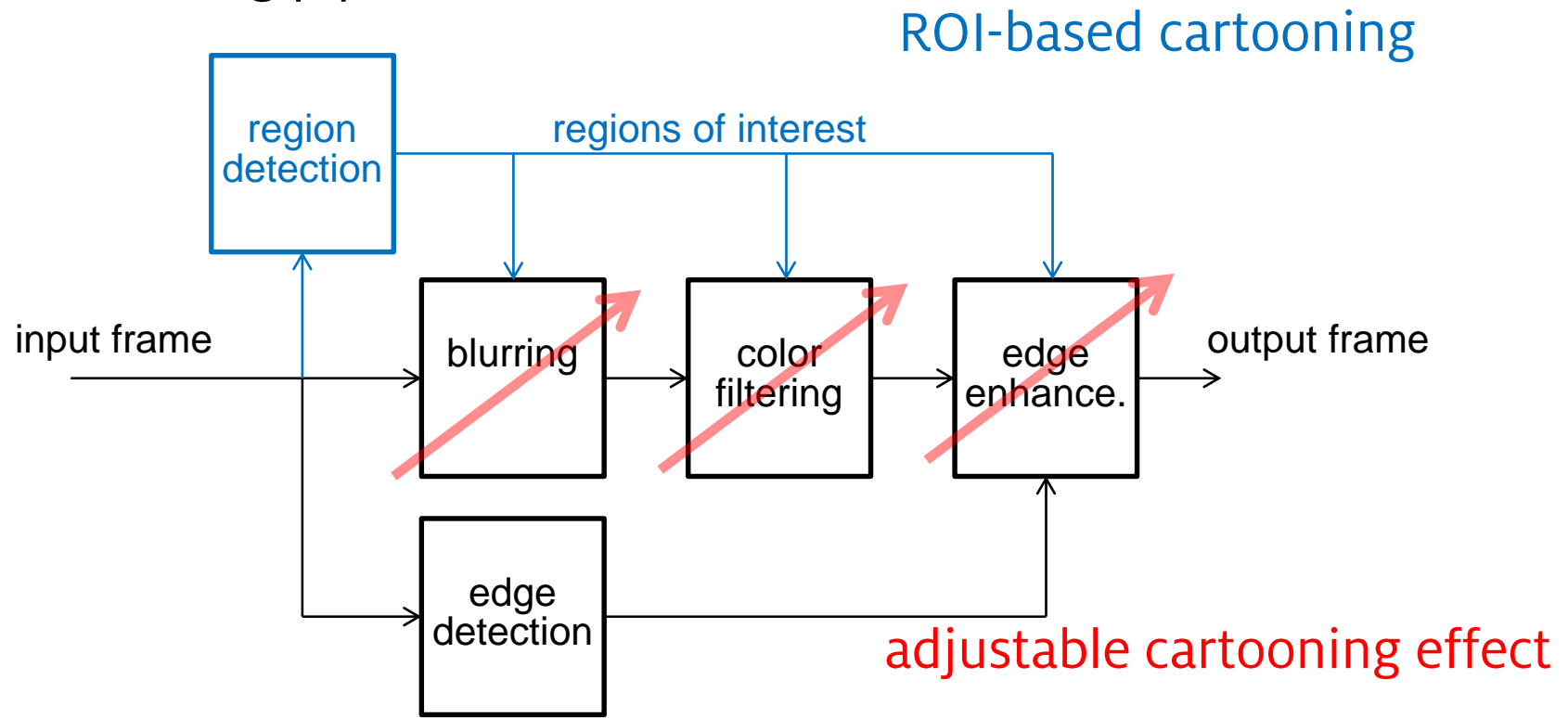


Bottom Side (not visible):

2MB SRAM, TPM Security IC, Power Management IC
(LiPo Charger), Micro USB Connector, Reset Button

Cartooning Privacy Filter

- Abstract parts or entire image by **blurring and color filtering**
- Cartooning pipeline



[Erdelyi et al. [Adaptive Cartooning for Privacy Protection in Camera Networks](#). In Proc. AVSS 2014.]

Adaptive Cartooning Filter



original



cartooning (small)



cartooning (std)

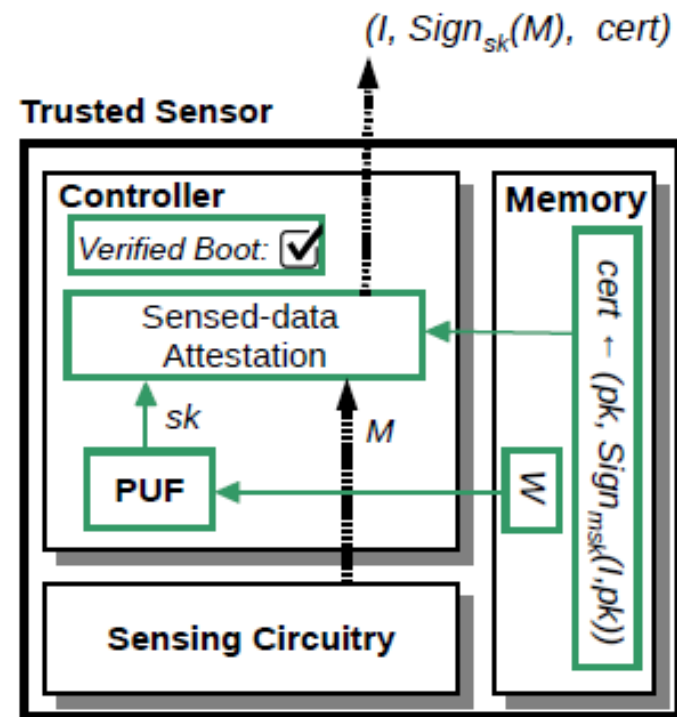


cartooning (strong)

TrustEYE Demo

Trustworthy Sensing

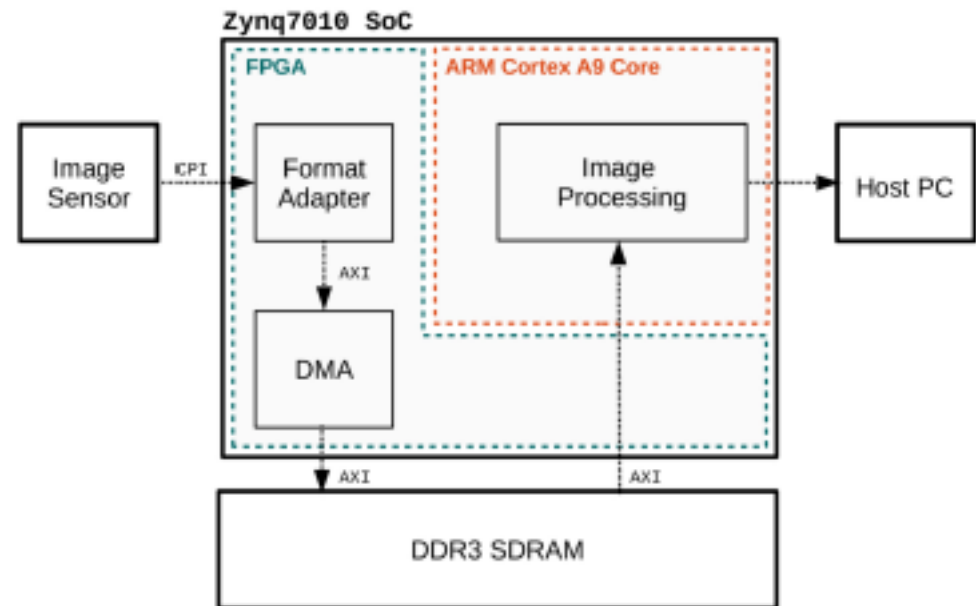
- Exploit **intrinsic hardware properties** as key storage and avoid dedicated security chip
- **Physically Unclonable Functions (PUFs)** extracts fingerprints
 - Secure key generation & storage
 - Attestation of sensed data
 - Verified boot of sensor controller
 - Little system overhead



[Haider, Hoerberl, Rinner. [Trusted Sensors for Participatory Sensing and IoT Applications based on Physically Unclonable Functions](#). In Proc. IoTPTS 2016]

Prototype SoC Implementation

- Xilinx Zynq 7010 (FPGA & dual Cortex ARM9 cores)
 - Ring-oscillator PUF with error correction to generate 128 bit keys
 - BLS signature scheme for data attestation
- Security overhead
 - 230 Bytes storage
 - 2210 logic cells
 - 6 ms for attestation



Conclusion

- Privacy protection important for commercial and private aerial imaging
- No single best protection method available. Tradeoff between protection, utility and resource usage
- Mostly image distortion used for protection, some can adapt the filter strength to scene
- Increase privacy awareness

Acknowledgements



Pervasive Computing group

Institute of Networked and
Embedded Systems

<http://nes.aau.at>

<http://bernhardrinner.com>

Funding support

- KWF/FWF “Trustworthy Sensing and Cooperation in Visual Sensor Networks”
- FFG “Progressing towards Secure, Cooperating Smart Cameras”