



Sensornetze

wie viele kleine Computer Großes leisten



**ALPEN-ADRIA
UNIVERSITÄT**
KLAGENFURT | WIEN | GRAZ

FAKULTÄT FÜR TECHNISCHE WISSENSCHAFTEN
Institut für Vernetzte und Eingebettete Systeme

Bernhard Rinner

Agenda



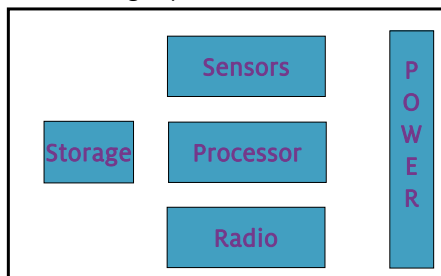
- Introduction to Sensor Networks
 - Enabling Technologies
 - Applications
- Selected Challenges
 - Topology
 - Networking
 - Synchronization
- Visual Sensor Networks
 - Research at PCG
- Relevance for Own Research

Introduction to Sensor Networks

Wireless Sensor Networks (WSNs)

- **Networks** of typically small, battery-powered, wireless devices, (“sensor nodes”, “motes”)
 - On-board processing,
 - Communication, and
 - Sensing capabilities.

Anatomy of a Sun SPOT



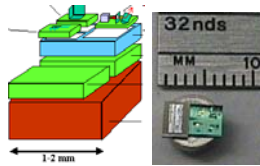
Sensor node schematics



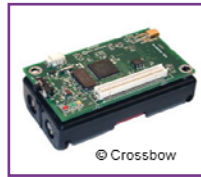
[© Oracle Labs]

Sensor Node Platforms

- From research prototypes to commercial products



The Vision
„Smart Dust“ UC Berkeley
late 1990's



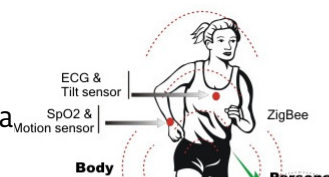
Research Prototypes
„Mica-2“
Crossbow 2004



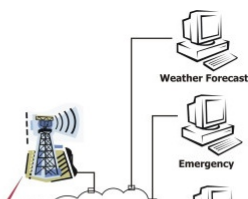
Commercial Products
„Mote-on-a-Chip“
Dust Networks, 2010

Some Applications of Sensor Networks

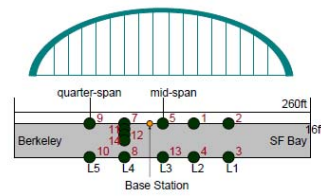
- Health



- Structural



- Agriculture



- Environment

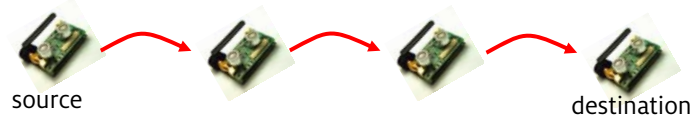


[Kim et al., ACM Sensys, 2006]

[Agrinet], [M. Weist, Harvard 2007]

Communication is Key

- **Wireless** communication is an enabling technology
 - Eases deployment
 - Enables mobility
 - Increases flexibility
 - Reduces costs
- Communicate **on demand** (ad hoc, spontaneous) with dynamic infrastructure
 - Nodes organize themselves into network
 - Data is transferred via **multiple hops**

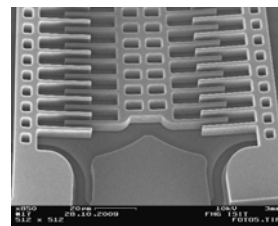


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7

But also ...

- Advances in **sensor** technology
 - **Micro electro-mechanical system** (MEMS) revolutionized sensing
 - Integration of mechanical and electrical components on single chip
 - Example: 3D accelerometer (in your cell phone)
- Embedded **processors** and integration
 - Moore's Law still valid
 - Trade-off between processing performance and power consumption



[© SensorDynamics]



[© ARM]

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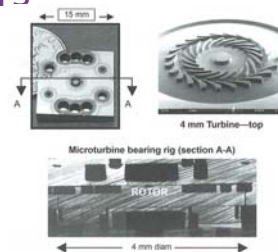
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The “Energy Problem”

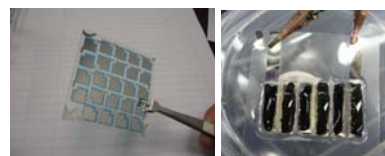
- Major sources of energy consumption
 - Sensing, computing, communication
 - High temporal variation
- Energy is the **scarce resource** for WSN. Several challenges
 - What **energy reservoirs** to exploit?
Constraints: availability, max. power, size, ...
 - How to **distribute power** over the network?
Energy provider and consumer might be dislocated.
 - How to **control the distribution**?
“The proper amount of energy in the right place at the right time”
- Sensor networks have always been a **“green” technology!**

Alternative Energy Reservoirs

- Maybe **micro-heat engines**
 - Exploit MEMS technology to build „internal combustion engines“
 - Expected power: 10-20 W
 - Still in early research/development phase
- Or **harvest energy** from environment
 - Organic semiconductors for exploiting indoor ambient light
 - Thin film batteries for storing energy
 - EnHANTs : energy harvesting networked active tags



[Handbook of Sensor Networks, Wiley]

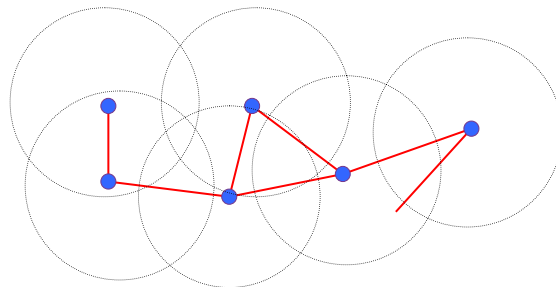


[Columbia University, CLUE]

(Selected) Challenges for Ad-hoc Networking

Topology Control

- Determine (bidirectional) communication topology
 - Which nodes are my neighbors ?
 - Is the network connected ?
- Sending power determines **radio coverage**



Topology Control (2)

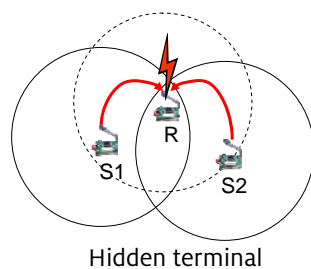
- **Critical Transmitting Range (CTR)**
 - Compute the minimum (common) transmitting range such that the network is connected.
 - If node locations are known -> CTR is the length of the longest edge of the minimum spanning tree (MST)

- Setting individual transmission rates
 - Objective: Minimize
 - “range assignment problem” (NP-complete)

$$\sum_1^n r_i^\alpha$$

Power-aware Media Access

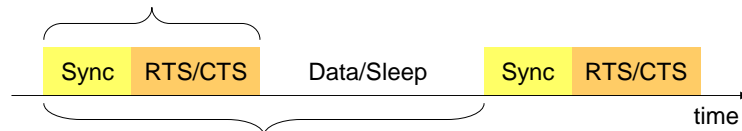
- Contention-based vs. contention-free media access
- In wireless communication **energy is “wasted”** by
 - Collisions
 - Overhearing
 - Idle listening
 - Protocol overhead



Carrier sense multiple access (CSMA)
 „listens before transmits“ a message, but collision can still occur.

Sensor-MAC (S-MAC) Protocol

- Use SYNC, RTS, CTS phases



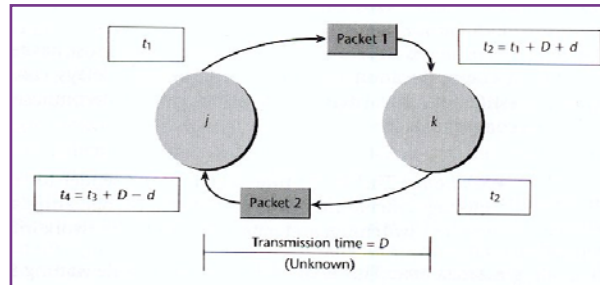
- Schedule active and passive periods for the radio
 - Low-duty-cycle operation (1-10%)
 - **Synchronization** of listen/sleep schedules required
 - At startup all nodes choose their own listen/sleep schedules
 - These schedules are shared with their neighbors to make communication possible between all nodes
 - Each node periodically broadcasts its schedule in a SYNC packet, which provides simple time synchronization

Time Synchronization

- Nodes operate independently
 - Local clocks may not be, or stay, synchronized
 - Clocks are inaccurate (eg., bias and drift)
- Synchronized clocks important for many applications
 - Sensor data interpretation
 - (Many) localization techniques require synchronization
 - Communication!
- Time synchronization in the “wired world”
 - (often) more accurate clocks are available
 - assume **constant communication delays**

Time Synchronization (2)

- Computing the clock **phase difference d**
 - Assumption: no clock skew, symmetric, constant delay D



[Zhao, Guibas. Wireless Sensor Networks, 2004]

- $d = (t_2 - t_1 - t_4 + t_3)/2$
- Even such simple setting requires to exchange 3 messages

Visual Sensor Networks

Smart Cameras as Sensor Nodes

- Differences to traditional sensor nodes
 - Process (much) more sensor data
 - Apply advanced analysis algorithms onboard
 - Avoid transferring raw image data
 - Energy!
- Various Prototypes



Rinner et al. (multi-DSP)
10 GOPS @ 10Watt



WiCa/NXP (Xetal SIMD)
50 GOPS @ 600mWatt



CMUcam3 (ARM7)
60 MIPS @ 650mW



CITRIC (PXA270)
660 MIPS @ 970mW

[Rinner et al. The Evolution from Single to Pervasive Smart Cameras. Proc. ICDCS 2008]

Resource-awareness in VSN

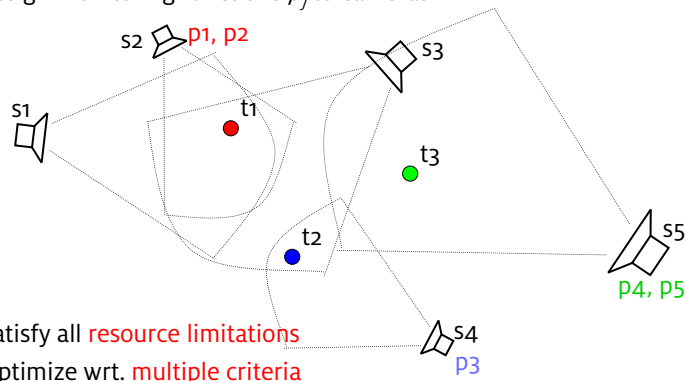
Lakeside Labs

- SRSnet Project: Smart Resource-Aware Multi-Sensor Network
 - Goal: deploy **audio/video sensor** network in biologically sensitive environments to autonomously **detect complex events**
 - Resource-awareness to run long from batteries
 - Partners: Lakeside Labs, NES, IST, Udine
- Configure the network such that detection task requires minimal energy



Resource-aware VSN Configuration

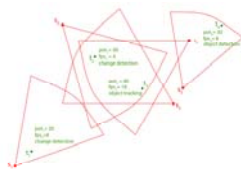
- VSN configuration as complex **coverage problem**
 - Select a set of cameras to cover all observation points t_i
 - Set the sensor (frame rate, resolution, PTZ) to achieve QoS
 - Assign monitoring functions p_j to cameras



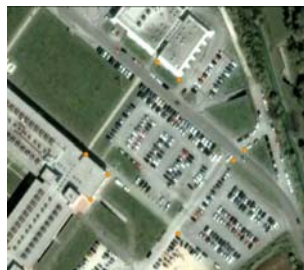
- Satisfy all **resource limitations**
- Optimize wrt. **multiple criteria**

Experimental Evaluation

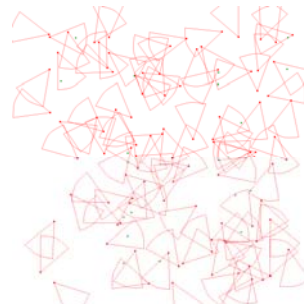
- Different scenarios with different activities
 - Various configurations, activities, observation points ...
 - Nodes execute real monitoring tasks (CV algorithms)



small



medium (campus@Udine)



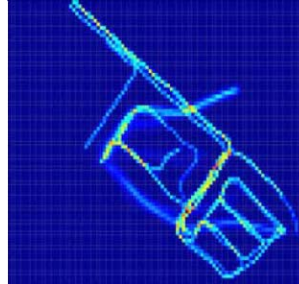
large (randomly generated)

Experimental Evaluation (2)

- Demonstration for monitoring campus scenario
 - Observation of person traces to compute the activity map (used to identify observation points)



person tracks



activity map

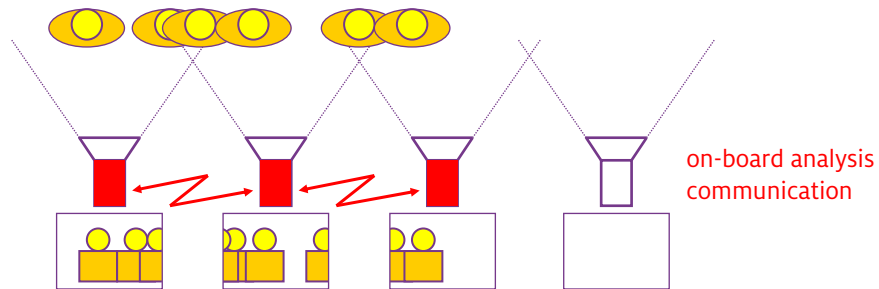
Self-aware smart camera networks

- EPiCS Project: Engineering Proprioception in Computing Systems
 - Goal: develop networks that react autonomously (requires self-awareness and self-expression)
 - Focus on smart camera networks
 - FP7 FET project with 8 European partners: U Paderborn, ETHZ, Imperial, U Oslo, U Birmingham, EADS, AIT,
- Demonstrate **autonomous multi-object tracking** in camera network



Multi-camera Tracking

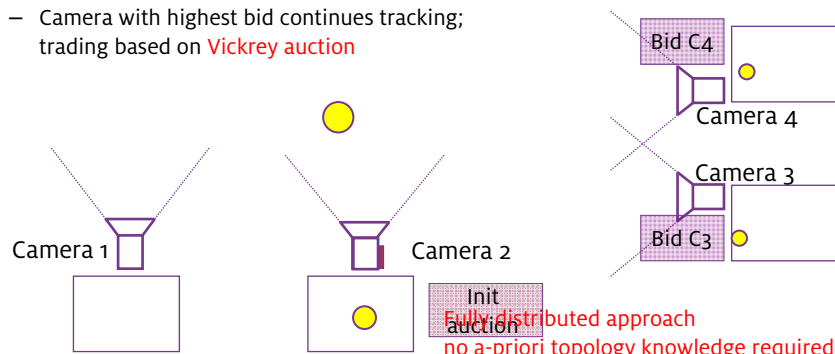
- Track mobile objects autonomously among multiple cameras



- How to select the next camera?
 - Requires knowledge of the topology (overlapping FOVs)

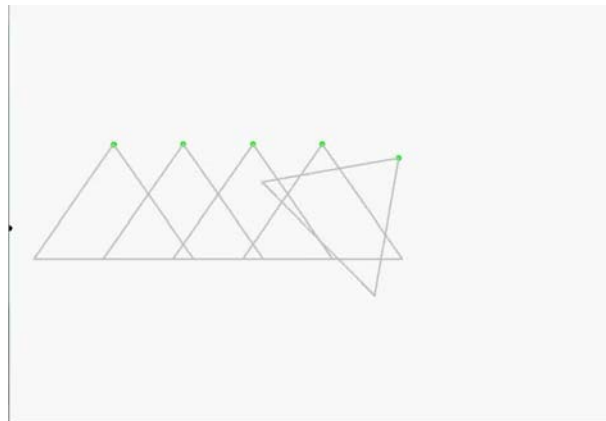
Virtual Market-based Handover

- Initialize **auctions** for exchanging tracking responsibilities
 - Cameras act as self-interested agents, i.e., maximize their own utility
 - Selling camera (where object is leaving FOV) **opens the auction**
 - Other cameras **return bids** with price corresponding to “tracking” confidence
 - Camera with highest bid continues tracking; trading based on **Vickrey auction**



Market-based Handover

- Utility function (each camera) $U_i(O_i) = \sum_{j \in O_i} u_i(j) = \sum_{j \in O_i} [c_j \cdot v_j \cdot \Phi_i(j)]$



visibility
tracking
decision
confidence

Simulation

green: tracking

yellow: shared FOV

red: trading (handover)

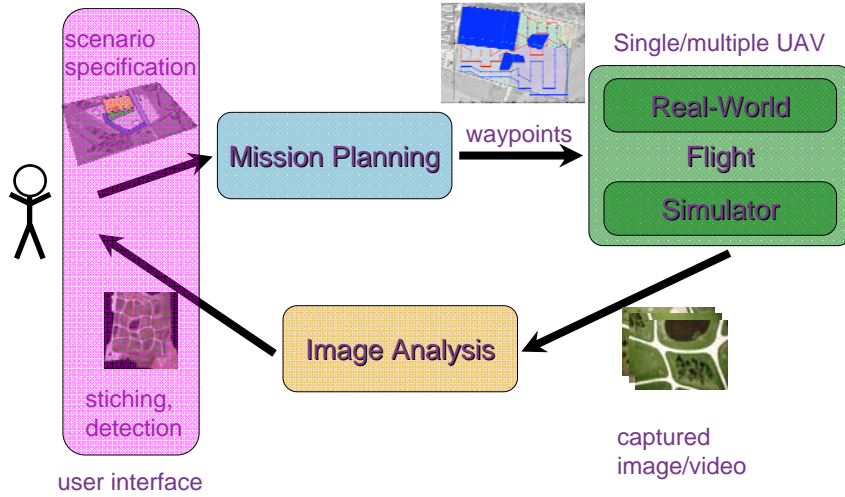
Collaborative Aerial Cameras

Lakeside Labs

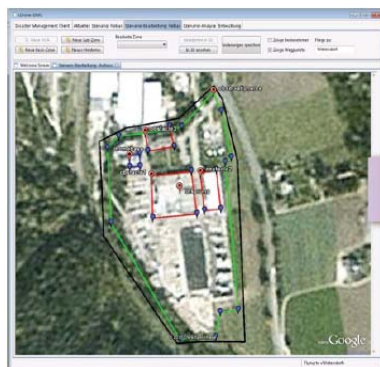
- Develop **autonomous multi-UAV** system for aerial reconnaissance
- Up-to-date aerial overview images are helpful in many situations:
"Google Earth with up-to-date images in high resolution"
- cDrones Project (NES, ITEC, AINF)
- Quadcopter** platform with onboard sensors and computation
- GPS receiver for autonomous **waypoint flights**
- Limitations on payloads, flight time, weather conditions



Autonomous UAV Operation



User Interface



Define high-level tasks,
i.e., observation area



Real-time overview image
and execution status

cDrones Videos



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<http://pervasive.aau.at/cDrones>

31

Are Sensor Networks
relevant for your research?

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32

Arg #1: Many open problems

- Wide field of challenging problems
 - Resource limitations
 - Energy-awareness
 - Embedded systems, integration
 - Sensors
 - Distributed sensing and processing
 - System-level software
- Interdisciplinary approach
 - Mathematics
 - Computer Science
 - Electrical Engineering
 - Material Sciences

Arg #2: Relevance and Impact

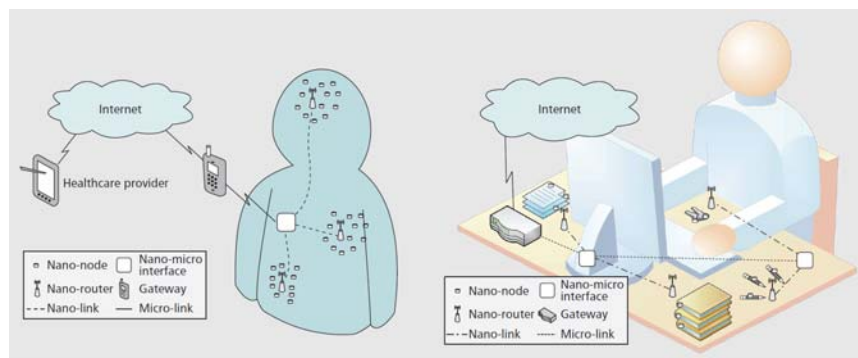
- Sensor networks help to solve “real” problems
 - Various applications
 - Standardization effort (ie., for “low power wireless”, wirelessHART)
- Manifestations of **some fundamental** problems, eg.,
 - (Self-)coordination of large networks
 - Coupling of “sensing-processing-networking-actuating”
 - Software engineering large networks
- Build your own network and conduct experiments!

Arg #3: Attractive for CS

- “Distributed systems” revisited, but
 - Strong resource limitations
 - Distributed sensing & processing
- Quality of Service provisioning
- Multimedia processing and distribution
- System-level software & Middleware systems

What next ?

- Nano Networks



[Akyildiz, Jornet. The Internet of Nano-Things. IEEE Wireless Communications. Dec. 2010]

Further Information

Web site: <http://pervasive.aau.at>

To probe further:

IEEE/ICE Summer School
Networked Embedded Systems
Klagenfurt Sep 3-7, 2011

ice.aau.at/ss-2011



www.avss2011.org



www.icephd.org